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1	Atmospheric correction and inherent optical property
2	estimation in the southwest New Caledonia lagoon using
3	AVNIR-2 high-resolution data
4	
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11 Abstract

Retrievals of inherent optical properties (IOPs) and Chlorophyll-a concentration (*Chla*) was investigated for AVNIR-2 images with 30-m spatial resolution and four bands in the southwest tropical lagoon of New Caledonia. We corrected the atmospheric and sea-surface reflectance iteratively through the retrieval of IOPs. After an additional correction of sea floor reflectance, the estimated IOPs and *Chla* agreed well with the in situ measurements even in the lagoon areas. This study provides a method to allowing a local optimal estimation of IOPs and *Chla* with a high resolution sensor by preparation of the candidate spectra for the target areas.

19

20 **1. INTRODUCTION**

21 1.1 Ocean color retrievals in the coastal areas

22 Ocean color retrieval is a challenge in the coastal areas but is a powerful tool for coastal 23 surveys. Sea surface reflection, including sunglint and whitecap, cause significant errors in the 24 ocean color estimation [1,2,3]. Sea surface reflection can be estimated from a statistic scheme 25 such as that presented by Cox and Munk [4] using low-resolution wind speed data from a 26 microwave radiometer, a scatterometer, or objective analysis data (e.g., [5,6]). However, the 27 correction based on the wind speed data is problematic in coastal areas because of fine 28 variations in the distribution of surface reflection due to variable winds, fetch length, and air-29 sea stability caused by the fine structure of the coastal geography. Several studies have 30 investigated high spatial resolution sunglint correction using hyperspectral bands or small scale 31 glint variations (e.g. [7,8]). Murakami and Frouin [9] demonstrated the possibility of sunglint (ρ_{e}) correction by using 500-m resolution near infrared (NIR) and shortwave infrared (SWIR) 32 bands of Moderate Resolution Imaging Spectroradiometer (MODIS). Higher (10-30 m) spatial 33 34 resolution sensors are expected to capture higher resolution spatial structures of ocean color 35 phenomena, especially in the coastal areas. However, they have a limited number of spectral 36 bands generally (e.g., without SWIR bands), which prevents the precise estimation of aerosol properties and the distinction between aerosol and sea-surface reflection. 37

In addition to these sensor limitations, coastal areas present difficulties for ocean color retrievals, *i.e.*, high NIR reflectance by suspended matter, complex Inherent Optical Properties (IOPs) due to various material inputs from the land, and bottom reflectance in the shallow areas. This explains why the blue/green ratio of remote sensing reflectance (R_{rs}), which is 42 traditionally used in the empirical estimation of chlorophyll-a concentration (*Chla*), does not
43 allow to calculate *Chla* in most cases of the coastal area (see Table 1 for symbol definitions
44 and units).

45 1.2 The New Caledonia lagoon

The New Caledonia lagoon is a large, almost continuous lagoon (22177 km²) lying in the 46 47 southwestern tropical Pacific from 20°S to 22°S and 166°E to 167°E (Fig. 1). Its heterogeneous 48 bathymetry (25 m as a mean depth) is due to a complex geomorphology with the presence of 49 sedimentary plains and a high proportion of shallow waters and numerous small sand islands 50 [10,11,12]. It is largely connected to the open ocean along its southern side, but only by narrow 51 passes in its southwestern side. It is an example of a coral reef lagoon system, which are very 52 sensitive to anthropogenic (nutrients, mining) perturbations [10,11] as well as to interannual 53 changes linked to the balance between dry El Niño and wet La Niña episodes [13,14], which are amplified in lagoons [12]. The central lagoon is characterized by oligotrophic to 54 mesotrophic waters (yearly average chlorophyll-a concentration of 0.25 ± 0.01 mg m⁻³) [15,16] 55 and exhibits a strong seasonal cycle with higher values in austral winter (July) or austral 56 57 summer (February) during nitrogen-fixing Trichodesmium blooms [17,18,19,20]. Upwelling at the barrier reefs [21] as well as internal waves in the southern part of the lagoon are two major 58 59 mechanisms of exchange with the sea, which can modify the phytoplanktonic assemblage [22].

Rain can also induce large chlorophyll enrichments in the lagoon [23]. With relatively low river inputs and a low turbidity range (0.20-16 g m⁻³), its trophic state is linked to spatial variations in flushing times [12,16,24]. Similarly to "optically complex" Case 2 European waters [25] or coastal bays [26], reflectance in the New Caledonia lagoon can be highly variable [27] as in other tropical environments [28], the Australian Great Barrier Reef [29], tropical estuaries [30] with a high influence of mineral particles from river discharge in bays [31] or colored dissolved organic matter (CDOM) [32]. Additionally, bottom reflectance, which represents a strong component in clear tropical shallow waters, may influence R_{rs} [33,34,35,36].

In order to improve the challenge of remote sensing in coastal environments [37], surface water IOPs (absorption and backscattering) were measured during several observation campaigns (e.g., coastal stations of Diapalis in 2003, Bissecote, Echolag, Valhybio, and the Valhybio Monthly Survey cruises from 2006 to 2010) in the lagoon and at different seasons [27,38,39]. The bathymetry of the Southern New Caledonia lagoon was compiled [12].

74 1.3 ALOS AVNIR-2

75 Advanced Land Observation Satellite (ALOS) has been operated by JAXA from 24 Jan. 76 2006 to 12 May 2011 and carried the Advanced Visible and Near Infrared Radiometer type 2 77 (AVNIR-2). AVNIR-2 has four spectral bands (centered at 463 nm, 560 nm, 652 nm, and 821 nm) with a 10-m Instantaneous Field of View (IFOV), a 70-km Field of View (FOV) and a 78 79 mechanical pointing function (by moving mirror) along the cross-track direction (±44 deg) for 80 effective global land observation. To achieve the ALOS mission objectives (cartography, 81 regional observation, disaster monitoring, resources survey, and technology development) and 82 to expand to quantitative applications, such as determination of vegetation density, coastal water color and their time dependencies, it is important to evaluate, improve and maintain the 83 84 radiometric calibration accuracy of AVNIR-2 (the pre-defined target is absolute error less than 85 10% [40]). The cross-calibration with MODIS indicated that the difference in top of atmosphere (TOA) radiance is less than 3% in the visible bands, and the temporal stability of
the radiance is less than 2% per 1000 days [41].

88 1.4 Scope of this study

89 Atmospheric and sea surface correction and IOP estimation were conducted using the four 90 bands of 30-m images averaged from AVNIR-2 10-m images (see section 2.1). The linear 91 matrix inversion (LMI) of IOPs [42,43,44] and atmospheric + surface reflection correction was 92 simplified to allow the four-band and high spatial resolution AVNIR-2 retrievals. Influence of 93 the bottom reflectance was reduced by using bathymetry data with a unique spectrum of 94 bottom reflectance. We compared the IOP estimates by different candidate IOP spectra 95 (observed particles + CDOM absorption (a_{pg}) and particle backscattering (b_{bp}) spectra) in the LMI scheme. Chla was estimated by two ways, from a statistical relationship with a_{pg} , or from 96 97 blue/green ratio of R_{rs} . For the series of AVNIR2 images available over the New Caledonia 98 lagoon, we validated the derived IOPs (a_{pg} and b_{bp}) and Chla using in situ measurements 99 around the AVNIR-2 observation dates.

100 **2. DATA AND METHODS**

101 2.1 AVNIR-2 images and radiance correction

AVNIR-2 data have 10-m spatial resolution but only 8-bit digital resolution with relatively low gain designed for the land-surface observations. We averaged AVNIR-2 TOA radiance images to a 30-m (0.0003 degrees equal latitude-longitude) grid to reduce the sensor noise before the atmospheric correction because the ocean-color signal is much lower than atmospheric one in the visible wavelengths. 107 The AVNIR-2 in-orbit radiometric performance was evaluated through a comparison with 108 Aqua MODIS by the cross-calibration scheme [41]. This scheme uses the TOA reflectance 109 functions of the satellite zenith angle estimated by Aqua MODIS observations within ±16 days 110 from the AVNIR-2 observation over temporally and spatially stable ground areas. The cross 111 calibration with the Aqua MODIS over the Antarctic snow fields allow us to correct AVNIR-2 112 bands 1-4 by the correction coefficients shown in Table 2. We calculated the TOA reflectance 113 of standard gas absorption conditions (column ozone = 343.8DU, water vapor = 14.19 mm, and 114 pressure = 1013.25 hPa) from the AVNIR-2 radiance observation as shown in Appendix.

115 Seventeen clear AVNIR-2 scenes were captured around the target area in the ALOS 116 mission period. The dates were 10 Sep. and 27 Sep. in 2006, 12 Feb., 3 Mar., 15 May, and 31 117 Jul. in 2007, 31 Oct. and 17 Nov. in 2008, 3 Sep. and 20 Nov. in 2009, 5 Jan., 3 Feb., 21 Mar., 118 8 Aug., and 22 Dec. in 2010, and 24 Mar. and 10 Apr. in 2011. Some scenes (27 Sep. 2006, 12 119 Feb. 2007, 31 Oct. and 17 Nov. 2008, 20 Nov. 2009, and 5 Jan. 2010) were covered by the 120 sunglint. Match-ups with in situ measurements were obtained (total 15 points) on 3 Sep. 2009 121 (time difference from the AVNIR-2 observation $\Delta D=5$ days), 17-18 Nov. 2009 ($\Delta D=2$ days), 122 and 11 Jan. 2010 ($\Delta D=6$ days).

123 2.2 Simplification of the atmospheric and surface corrections

124 At each solar and sensor geometry condition, the TOA reflectance ρ_b , for which gaseous 125 absorption is normalized by standard atmosphere condition, can be described as follows.

126
$$\rho_t(\lambda_b) = \rho_r(\lambda_b) + \rho_a(\lambda_b, \tau_a, M) + t(\lambda_b, \tau_a, M) \times \rho_g(\lambda_b) + T(\lambda_b, \tau_a, M) \times \rho_{wc}(\lambda_b) + T(\lambda_b, \tau_a, M)$$
127
$$\times \rho_w(\lambda_b)$$
(1)

128 where ρ_r is the atmospheric molecule reflectance, ρ_a is the aerosol reflectance, including aerosol-molecule interaction, ρ_w is the water-leaving reflectance, ρ_g is the sunglint reflectance, 129 130 ρ_{wc} is the whitecap reflectance, t is the atmospheric direct transmittance (sun-surface + surface-131 satellite), and T is the direct + diffuse transmittance (sun-surface + surface-satellite), λ_b is the 132 center wavelength of sensor spectral band, τ_a is the aerosol optical thickness, and M is the 133 aerosol model. ρ_g can be estimated by a statistical equation [4] using wind speed and the 134 refractive index of water at each wavelength. However, there is no simultaneous 30-m resolution wind speed data, and the statistical relation is not always consistent with the real 135 136 complicated sea surface.

137 The Rayleigh scattering of ρ_r and T (at $\tau_a=0$) can be estimated by atmospheric radiative 138 transfer simulation. In order to achieve this, we used Pstar2b [45], which takes into account 139 atmospheric polarization, provided by the National Institute for Environmental Studies (NIES) 140 GOSAT project and the OpenCLASTR project [46,47,48]. We prepared look-up tables of 141 $\rho_r(\lambda_b)$ (including sea-surface reflection with wind speed = 0) and T at each geometric condition. 142 The Rayleigh-scattering subtracted reflectance (ρ_{agw}) can be described by the following Eq. 143 (2).

144
$$\rho_{agw}(\lambda_b) \equiv (\rho_t(\lambda_b) - \rho_r(\lambda_b)) / T(\lambda_b, \tau_a=0)$$

145 =
$$[\rho_a(\lambda_b, \tau_a, M) / T(\lambda_b, \tau_a=0) + t(\lambda_b, \tau_a, M) / T(\lambda_b, \tau_a=0) \times \rho_g(\lambda_b) + T(\lambda_b, \tau_a, M) / T(\lambda$$

146
$$\tau_a = 0 \times \rho_{wc}(\lambda_b)] + T(\lambda_b, \tau_a, M) / T(\lambda_b, \tau_a = 0) \times \rho_w(\lambda_b)$$
(2)

147 The $T(\lambda_{b=1,2,3 \text{ and } 4}, \tau_a=0)$ are about 0.83, 0.91, 0.95, and 0.98 respectively at $\theta_{sun}=\theta_{sat}=0$. $T(\lambda_b, \tau_a, \tau_a, \tau_a=0)$ are about 0.83, 0.91, 0.95, and 0.98 respectively at $\theta_{sun}=\theta_{sat}=0$. $T(\lambda_b, \tau_a, \tau_a, \tau_a, \tau_a=0)$ can be approximated as 1.0 because it is >0.9 when $\tau_a<0.5$. We simplified 149 aerosol and surface reflection ($\rho_{ag} \equiv \rho_a + \rho_g$) as the following form (Eq. (3)) because ρ_{ag} is to 150 be spectrally smooth and can be approximated by a power function α of the wavelength ratio in 151 most cases [49].

152
$$\rho_{ag}(\lambda_b) \cong \rho_{ag}(821 \text{ nm}) \times (\lambda_b \times c_{wl} / 821 \text{ nm})^{\alpha}$$
 (3)

153 The spectral shape of ρ_{ag} was improved by a correction factor, c_{wl} (= 0.99 at band 3 (652 nm) 154 and 1.0 at other bands), which was derived from the atmospheric radiative transfer simulation 155 (the root mean square error of ρ_{ag} is 0.004 at 463 nm for the tropospheric, oceanic, and their 156 mixed aerosols in the case of aerosol optical thickness = 0.3 and air-mass pl < 4). The α ranged 157 from -0.5 to +0.3 for the oceanic aerosols and from -1.8 to -1.2 for the tropospheric aerosols.

158 The variables about the aerosol and surface reflection, α and ρ_{ag} (821 nm), could be 159 estimated using the AVNIR-2 data through an iteration with the IOP retrieval described in the 160 next section. The approximation of Eq. (3) enabled quick processing including the iteration 161 scheme.

162 2.3 IOP and water-leaving reflectance estimation

Most of the IOP algorithms [50] are based on the equation of remote sensing reflectance below the surface (r_{rs}) , the total absorption coefficient (a) and the backscattering coefficient (b_b) proposed by Gordon et al. [51].

166
$$r_{rs}(\lambda) = g_1 \times u(\lambda) + g_2 \times u(\lambda)^2$$
(4)

167
$$a(\lambda) = a_w(\lambda) + a_{ph}(\lambda) + a_d(\lambda) + a_g(\lambda)$$
(5)

168
$$b_b(\lambda) = b_{bw}(\lambda) + b_{bp}(\lambda)$$
(6)

169 with

170
$$u(\lambda) = b_b(\lambda) / (b_b(\lambda) + a(\lambda))$$
(7)

171 where g_1 =0.0949 and g_2 =0.0794 [51]. a_w , a_{ph} , a_d , and a_g are the absorption spectra of water, 172 phytoplankton, detritus, and CDOM respectively. b_{bw} and b_{bp} are backscattering coefficients of 173 water and particles. Remote sensing reflectance above the surface, R_{rs} is estimated from r_{rs} 174 using the relation from [51,52] as:

175
$$R_{rs}(\lambda) = 0.52 \times r_{rs}(\lambda) / (1 - 1.7 \times r_{rs}(\lambda)).$$
 (8)

176 The water-leaving reflectance ρ_w in (1) is simply calculated from the R_{rs} .

177
$$\rho_w(\lambda) = \pi \times R_{rs}(\lambda) \tag{9}$$

We used the LMI scheme [42,43,44] to estimate IOPs. The scheme requires a_w , b_{bw} , and model spectra, a_{ph} ', a_{dg} ' (absorption of detritus + CDOM), and b_{bp} ', which is normalized at a specific wavelength (442 nm was used in this study). We used a_w and b_{bw} values from [53,54] weighted by the AVNIR-2 spectral response (shown in Table 3). Wavelength functions of a_{dg} and b_{bp} were as follows.

183
$$a_{dg}(\lambda_b) = a_{dg0} \times a_{dg}(\lambda)' \tag{10}$$

184
$$b_{bp}(\lambda_b) = b_{bp0} \times b_{bp}(\lambda_b)$$
 (11)

185 where

186
$$a_{dg}(\lambda)' = \exp(S \times (\lambda - 442)) \tag{12}$$

187
$$b_{bp}(\lambda)' = (\lambda/442)^Y$$
 (13)

where a_{dg0} is a_{dg} at 442 nm, b_{bp0} is b_{bp} at 442 nm, S = -0.010 or -0.018, and Y = -1.4, 0, or +2. S = -0.010 and Y = -1.4 were derived from the New Caledonia in situ measurements of a_{dg} and b_{bp} respectively.

191 The inversion process was simplified to use only two IOP parameters, $a_{pg} (\equiv a_p + a_g \equiv a_{ph} + a_{dg})$ and b_{bp} , and two AVNIR-2 bands, band 1 (463 nm) and band 2 (560 nm). We set the 193 a_{pg} ' as follows.

194
$$a_{pg}(\lambda_b) = a_{pg0} \times a_{pg}(\lambda_b)' = a_{pg0} \times \{ (1 - r_{pg}) \times a_{ph}(\lambda_b)' + r_{pg} \times a_{dg}(\lambda_b)' \}$$
(14)

where a_{pg0} is a_{pg} at 442 nm. The ratio of a_{ph} and a_{dg} at 442 nm, r_{pg} , was set to 0.52 / (1 + 0.52) considering the normal conditions observed in the New Caledonia in situ data [32]. We can estimate two parameters of IOPs, a_{pg0} and b_{bp0} , by the iteration processes of the IOP forward calculation and LMI [42,43,44].

199 If we have an initial value of a_{pg0} and b_{bp0} , ρ_w can be calculated by (4)-(14). Using the ρ_w , 200 ρ_{ag} at 652 nm and 821 nm can be calculated using molecular scattering corrected reflectance 201 derived from satellite observation (ρ_{agw}) as:

202
$$\rho_{ag}(\lambda) = \rho_{agw}(\lambda) - \rho_{w}(\lambda) \tag{15}$$

203 where $\lambda = 652$ nm and 821 nm. Considering an approximation of Eq. (3), α can be calculated 204 by Eq. (16).

205
$$\alpha = \log(\rho_{ag}(652 \text{ nm}) / \rho_{ag}(821 \text{ nm})) / \log(652 \times c_{wl} / 821)$$
 (16)

206 Then, ρ_w at 463 nm and 560 nm are calculated by Eqs. (3) and (15). Using the ρ_w at the two 207 visible bands, a_{pg0} and b_{bp0} can be calculated by the LMI [42,43,44].

208 The iteration process to derive the final value of a_{pg0} and b_{bp0} is shown in Fig. 2. The first 209 process aims to estimate α except for shallow areas (bathymetry<20m) where the bottom 210 reflectance can influence r_{rs} . The iteration was repeated to find optimal values of a_{pg0} and b_{bp0} 211 by minimizing the difference between b_{bp0} preset in Eq. (11) and b_{bp0} calculated by the 212 inversion matrix. The initial value of a_{pg0} was set to 0.01, which does not affect the final a_{pg0} 213 estimates because a_{pg} is relatively small in the total *a* in red and NIR wavelengths. The sub-214 process is repeated until $|a_{pg0} - a_{pg0}'| < 0.0001$ (practically less than four times in most pixels) with revision of a_{pg0} and the search range of b_{bp0} (b_{bp0} ^(max)) which is set by ρ_{ag} at 821 nm and 215 the extremely high $a_{pg0} = 20 \text{ m}^{-1}$. After completing the first process, we smoothed α for each 216 0.1 deg \times 0.1 deg area to reduce the AVNIR-2 sensor noise and extrapolate to the shallow 217 (<20m) areas where we did not estimate α in the first process. The second process derives ρ_{ag} 218 a_{pg} , b_{bp} , and R_{rs} for every 30-m grid using the same equations. We can derive IOPs and R_{rs} at 219 220 any wavelengths (AVNIR-2 bands at 463 nm and 560 nm and the wavelengths of the in situ 221 measurements at 442 nm and 555 nm) using the IOP spectra $a_{pg}(\lambda)$ ' and $b_{bp}(\lambda)$ ' (see section 222 2.5).

223 2.4 Chlorophyll-a estimation

224 Chlorophyll-a was estimated by regression of $a_{pg}(442 \text{ nm})$ and the empirical blue/green as 225 follows:

226
$$\log_{10}(Chla) = 0.9706 + 1.1835 \times \log_{10}(a_{pg}(442 \text{ nm}))$$
 (17)

227
$$\log_{10}(Chla) = 0.1464 - 1.7953 r + 0.9718 r^2 - 0.8319 r^3 - 0.8073 r^4$$
 (18)

228 where

229
$$r = \log_{10}(R_{rs}(463 \text{ nm}) / R_{rs}(560 \text{ nm})).$$
 (19)

The relationship between *Chla* and a_{pg} (443 nm) was derived from a_{pg} and the fluorometric chlorophyll-a data included in the bio-Optical Marine Algorithm Data set (NOMAD) [55] (Fig. 3). The MODIS OC2M-HI equation developed by the NASA Ocean Biology Processing Group (OBPG) using the NOMAD database [6] was used for the two channel equation becauseAVNIR-2 has only two channels in blue and green wavelengths.

235 2.5 In situ bio-optical measurements

236 Field measurements of the two IOPs, the absorption coefficient, a, and the backscattering 237 coefficient, b_b , were obtained at stations in the southwest part of the lagoon (Fig. 1) during 238 various seasons from 2006 to 2010. The b_b was measured with a Hydroscat-6 profiler (H6: HobiLabs, wavebands (λ) centered at 442, 488, 510, 550, 620 and 670 nm with a bandwidth of 239 240 10 nm for the 442–550 nm bands and 20 nm for the 620 and 670 nm bands) [19,27]. The 241 particulate back-scattering coefficient, $b_{b\nu}(\lambda)$, was calculated by subtracting from $b_b(\lambda)$ the theoretical "pure water spectrum", $b_{bw}(\lambda)$ (calculated as $b_{bw}(\lambda) = 0.5 \times b_w(\lambda)$) [51]. The 242 243 particulate absorption coefficient, $a_p(\lambda)$, was measured with the filter-pad technique [56] using 244 water samples filtered onto 25-mm GF/F Whatman filters. For pigments, the filters were dipped in 5.4 ml 100% acetone (final concentration 90% acetone taking into account water 245 246 retention by the filter, e.g., 0.621 ± 0.034 ml) and ground with the freshly broken end of a glass 247 rod for chlorophyll and phaeopigment extraction [57]. For comparison with the satelliteestimated *Chla*, we used the sum of chlorophyll a and divinyl chlorophyll a, *Chla* (in mg m⁻³), 248 249 as measured by spectrofluorometry, and well correlated with fluorometry in the Caledonian lagoon [15,27]. 250

For the LMI, we prepared the model spectra of a_{pg} and b_{bp} optimized for the New Caledonia in situ samples (six samples of a_{ph} and a_{dg} in 2003, and 112 samples of b_{bp} in 2006-2010). The samples of a_{ph} and a_{dg} were distributed around the lagoon of the southeast New Caledonia, but not near bays of the mainland. The spectral shape a_{dg} ' and b_{bp} ' (relative values from λ =442 nm) were modeled by Eqs. (12) and (13) respectively. The model spectra from the averages of the New Caledonia measurements were used as the standard in sensitivity tests described below.

We tested the sensitivity of different sets of model spectra: (A) a_{pg} ' and b_{bp} ' from the New Caledonia measurements (e.g., same as the above); (B) same as (A) but a_{ph} ' from a picoplankton spectra [58]; (c) same as (A) except for a_{ph} ' from a microplankton spectra [58]; (D) same as (A) except for a_{dg} ' with S = -0.018; (E) same as (A) except for b_{bp} ' with Y = 0.0; and (F) same as (A) except for b_{bp} ' with Y = -2.0 (Fig. 4). These a_{ph} ' spectra are listed in Table 3.

264 2.6 Correction of sea floor reflection

The R_{rs} and IOP estimation might be influenced by bottom reflectance especially in low absorption and shallow areas, such as site G003 near the barrier reef (11 meters depth, bottom composed of white sands). r_{rs} in shallow areas was approximated by the following equation from [59]:

269
$$r_{rs} \sim r_{rs}^{dp} \times [1 - \exp\{-\kappa H \times (1/\cos\theta_{0w} + D_u^C/\cos\theta_w)\}]$$

270
$$+ \rho_b / \pi \times \exp\{-\kappa H \times (1/\cos\theta_{0w} + D_u^B/\cos\theta_w)\}$$
(20)

where ρ_b is the bottom albedo, *H* is the bottom depth, θ_{0w} is the subsurface solar zenith angle, θ_w is the subsurface viewing angle from nadir ($\theta_w = \sin^{-1}(1 / 1.34 \times \sin \theta_a)$), θ_a is the abovesurface angle), r_{rs}^{dp} is the remote-sensing reflectance for optically deep water, and κ is the attenuation coefficient ($\kappa(\lambda) = a(\lambda) + b_b(\lambda)$). D_u^C and D_u^B are optical path-elongation factors for scattered photons from the water column and bottom respectively, which are described by functions of $u(\lambda)$ following [59].

Because ρ_b is unknown at each image grid in this study, we used a ρ_b spectrum of coral sand shown by Fig. 6 of [60] ($\rho_b = 0.33$ and 0.47 at 442nm and 555nm respectively). The similar ρ_b spectra of the sandy sea bottom were reported around the coral reef system by [61,62]. We use *H* compiled in [12] (Fig. 5). Attenuation coefficient, $\kappa(\lambda)$, is iteratively calculated through the IOP estimation described in section 2.3 by changing *H* from enough deep depth (1000m) to the actual sea-floor depth gradually. Such an approach has been used to retrieve bathymetry [36].

284 2.7 MODIS ocean color products

NASA OBPG Aqua MODIS products, R_{rs} at 443 nm, R_{rs} at 555 nm, and *Chla* (processing version 2009.1) [6], were used for the comparison to our results. The global accuracies of the MODIS data set, reported as the median absolute percent differences of normalized waterleaving radiance (L_{wn}) at 443 nm, L_{wn} at 555 nm, and *Chla* from global in situ observations, are 18%, 17%, and 37% respectively [6,63]. We selected clear MODIS scenes ±1 day from AVNIR-2 observations or between the AVNIR-2 and in situ observation dates.

291 **3. RESULTS**

292 3.1 R_{rs} and ρ_{ag}

Figure 6 shows results of the ρ_{agw} (463 nm), ρ_{ag} (463 nm), α , ρ_w (463 nm) without bottom correction, and ρ_w (463 nm) with bottom correction on 17 Nov. 2008 and 3 Sep. 2009. On 17 Nov. 2008, the area was covered by sunglint (brighter on the right side in Figs. 6a and 6b). ρ_{ag} (Fig. 6b) showed small-scale structures of the surface reflection caused by the winds and geographical features. α (Figs. 6c and 6h) was smoothed in each 0.1 deg × 0.1 deg grid after the first process ((a) in Fig. 2). The estimated ρ_w (Fig. 6d) was very smooth offshore and showed fine structures inside the lagoon. On 3 Sep. 2009, aerosol with small clouds extended northwest to southeast over the area (Fig. 6g). The aerosol pattern was removed effectively in the ρ_w image (Fig. 6i) by subtracting ρ_{ag} (Fig. 6g) from ρ_{agw} (Fig. 6f). High reflectance areas remained inside the lagoon with a dark area along the outside of the barrier reef.

The comparison between AVNIR R_{rs} and MODIS R_{rs} at 442nm (or 443 nm) and 555 nm is shown in Fig. 7. AVNIR-2 R_{rs} at 555nm appears slightly higher, but the results are closely correlated (0.77 and 0.54 at 442 nm and 555 nm, respectively, and the Root Mean Square Difference (RMSD) was about 40% and 63% of the average R_{rs} for AVNIR-2 and MODIS, respectively) except for some samples at the shallow stations (*e.g.*, B50 and B03). An outlier at station G003 in Fig 7a (AVNIR-2 R_{rs} at 442 nm is about 0.03) seemed to be influenced by cloud edge in the AVNIR-2 image on 31 Jul. 2007.

Figures 6e and 6j show the AVNIR-2 ρ_w at 463nm with the correction of bottom reflectance. The correction decreases ρ_w inside of the lagoon (*e.g.*, at stations M33 and G003) and reduces the pattern of the bathymetry (seen Fig. 5) in most areas in the ρ_w images. However, it seems to cause overcorrection in some areas, *e.g.*, around the islands and the barrier reef.

315 **3.2** *a*_{pg} and *b*_{bp}

Figures 8a and 8b shows a_{pg} at 442nm and b_{bp} at 555nm without the bottom correction (using model spectra (A) in Table 4). a_{pg} was high along the coast and in bays near the main land. On the other hand, b_{bp} was high inside the lagoon especially at shallow bottom areas (e.g., G003). Scatter plots between the in situ ($a_p \times 1.52$) and the AVNIR-2 a_{pg} and b_{bp} estimates are shown in Figs. 9a and 9b. They show that AVNIR-2 a_{pg} is well correlated with in situ values for a_{pg} (r = 0.91 in Fig. 9a) even though the factor 1.52 may vary with changing proportions of a_p or a_g in $a_{pg} = a_p + a_g$. AVNIR-2 b_{bp} showed a high correlation coefficient (about 0.94 at 555 nm), but some values of b_{bp} were higher than the in situ b_{bp} . The overestimated samples were found in shallow areas (3.6 m, 6 m, 5m, and 11 m at stations B50, B03, Ile aux Canards and G003 respectively).

326 Figures 8c and 8d show a_{pg} and b_{bp} with the bottom reflectance correction on 3 Sep 2009. The correction decreased a_{pg} and b_{bp} in the lagoon areas. The comparison to the in-situ 327 328 observations (Figs. 9c and 9d) showed that the correction improved the agreement especially at 329 stations M33, Ile aux Canards, and G003 where the bottom depth is shallow and a_{pg} is relatively low. The AVNIR-2 a_{pg} was still higher than the in-situ a_{pg} at stations B50 and B03 330 331 around the Boulari Bay. Bias of a_{pg} (b_{bp}) were improved from 0.188 to 0.118 (from 0.023 to 332 0.015), and RMSD of a_{pg} (b_{bp}) from 0.489 to 0.290 (from 0.042 to 0.025) by the bottom 333 correction.

Table 4 shows the results for the fifteen match-ups by using different spectra of a_{pg} and b_{bp} . Superscripts – and + show results with smaller or larger bias or RMSD (statistically significance level of 95%) than ones by the model spectrum (A). The results depended on the model spectra significantly, and the model (D) brought the smallest RMSD of both a_{pg} and b_{bp} with the bottom reflectance correction. Note that the microplankton for a_{ph} [58] gives larger RMSD than the measured around New Caledonia. Similarly, a slope of Y = -2 is too different from those measured and would not allow a proper retrieval of IOPs from AVNIR-2. Figures 341 9e-9h show the scatter plots by the model spectrum (D). RMSDs of a_{pg} and b_{bp} are significantly 342 decreased (especially stations B50 and B03) by the optimal model spectrum.

343 3.3 Chlorophyll-a concentration

344 Figures 10 and 11 show the comparison among *Chla* estimated from a_{pg} (by the optimal 345 model (D)), Chla calculated by OC2M-HI (using R_{rs} by AVNIR-2), and the MODIS standard 346 (OC3M) 1-km Chla. Chla estimated from a_{pg} (Figs. 10a and 11a) was slightly smaller than 347 Chla determined by other algorithms in the lagoon areas (e.g., sites B08 and Ile aux Canards in 348 Figs. 10 and 11). The AVNIR-2 OC2M-HI Chla was larger than indicated by the in situ data 349 and similar to the MODIS standard value in the lagoon (see around sites M33 and G003 in Figs. 350 10b, 10e, and Figs. 11b and 11e). The scatter plots show that Chla from a_{pg} provides the best 351 agreement among the three methods in the lagoon (RMSD=0.47, 0.61, and 0.60 in Figs. 10a, 352 10b, and 10e). The MODIS data at stations M33 and GD10 were scattered because they were 353 too near the coast or the lagoon islands compared to the 1-km resolution products.

Figures 11c and 11d show results with the bottom correction. OC2M-HI *Chla* (Fig. 11d) was calculated by R_{rs} from r_{rs}^{dp} (Eq. (8)). Usual high biases of a_{pg} and b_{bp} in the shallow areas (B50, B03, and Ile aux Canards) around lagoon islands were decreased by the correction (Figs. 8c and 8d). It reduced overestimate of *Chla* by both a_{pg} and OC2 schemes, and improved the agreement with the in-situ matchups inside the lagoon (Figs. 10c and 10d).

359 4. DISCUSSION

360 4.1 a_{pg} and b_{bp} spectra

361 Agreement with in situ data was dependent on spectra of a_{pg} and b_{bp} (Table 4). For example, 362 the a_{ph} spectrum of microplankton [58] (model C) and b_{bp} spectrum of Y=-2.0 (F) caused 363 worse results than the spectrum modeled from New Caledonia in situ measurements (A) (Table 4). The agreement may be improved further if we optimize the spectra to more specific water 364 365 types, e.g., bays near the main land, middle-lagoon waters, and waters outside of the barrier 366 reef (e.g., open ocean). For example, modification of spectral slope of a_{dg} improved the IOP estimate especially around the Boulari Bay (model (D) in Fig. 9). The accuracies of the best 367 368 results (r=0.91 and r=0.75 in Figs. 9g and 9h respectively) were better than ones by Quasi-Analytical Algorithm (QAA) [52,64] by using 1km MODIS Aqua Rrs data (r=0.84 and 0.72 369 370 for a_{pg} 443nm and b_{bp} 555nm respectively (Figures of QAA results are not shown here).

Such an optimization with the best-candidate spectra can be a useful way to obtain locallyoptimized environmental monitoring from satellite observations with theoretical understanding
of the local optical environment.

This study cannot determine spectral models such as the ratio between a_p and a_g (or a_{ph} and adg), because AVNIR-2 has only two channels in the blue and green wavelengths. More bands at 250 m to 300 m of spatial resolution from sensors such as SGLI and OLCI may be able to improve the discrimination of the IOPs.

The IOP retrieval schemes have been developed for observations by narrow (about 10-20nm) band-width sensors, estimates of absorption coefficients by the wide band can cause errors reaching about 20% [65] by the QAA [52,64] through the integration of the IOP spectra in the band wavelengths. Our estimates rely on relatively wide bands (about 90nm) of AVNIR-2. We confirmed our retrieval of a_{pg} by the LMI can change about 20% (mostly overestimated) using simulated *Rrs* from our in-situ a_{pg} and b_{bp} . The error is still much smaller than the error due to difference of the model IOP spectra, however, it will need to be considered for more precise estimate in the future.

386 4.2 Aerosol and sea surface reflection estimation

Most of the iteration schemes for the atmospheric correction use the relationship between NIR R_{rs} and *Chla*. This study uses the relationships among a_{pg} , b_{bp} , ρ_{ag} , and α based on the convergence of b_{bp} . This scheme can avoid negative IOPs by tuning the aerosol parameters α and ρ_{ag} in the iteration process. Another merit of this aerosol estimation is the fast processing time (2-3 minutes for our study area (2001×1334 pixels) by a wide-use PC Linux machine) because it does not require time to access the aerosol look-up table that is used in the standard ocean color atmospheric correction algorithms.

394 The New Caledonia lagoon area has a relatively clear atmosphere compared to coasts in the 395 northern hemisphere, such as the Asian coasts. This scheme does not consider absorptive 396 aerosols that cannot be described by the simple Eq. (3). For more complex atmosphere 397 (aerosol) conditions, more bands may be necessary than the two that were used here for the 398 aerosol characterization (this study used 652 nm and 821 nm). If the sensor has lower noise and 399 SWIR bands (e.g., MODIS 500 m bands and SGLI 250m band), we may be able to estimate α 400 at each pixel and obtain more realistic measurements of α and ρ_{ag} . However, the absorptive 401 aerosol correction may still be difficult using the simple Eq. (3).

402 4.3 The bottom effect

403 AVNIR-2 b_{bp} seemed to be influenced by the bottom reflectance. Bottom sands can be seen 404 from satellite if bathymetry is shallow. For example, the bottom depth of the station G003 is 11 405 m with a relatively low a_{pg} . Agreement between AVNIR-2 IOPs and in situ IOPs were 406 improved by considering the bottom reflectance generally, but they seemed to be overcorrected 407 in some areas around the islands and along the barrier reef (Fig 6j). They are supposed to be 408 influenced by coverage of live corals or sediment from the land, which may cause a different 409 spectrum of the bottom reflectance from the coral sand reflectance [60,61,62]. This indicates 410 that our IOP estimation could be improved if the precise bottom depth and real bottom 411 reflectance are used [36].

412 4.4 Cloud shadow and adjacent scattering

For the 10-m resolution data, it is important to consider cloud shadow and sea surface reflection of scattered light from the cloud bottom. Identification of clouds around the coast (including over the land) and geometric calculation considering the cloud height are required. In addition, the clouds and land area can influence the coastal ocean color estimation, which is known as the adjacent effect [66]. The influence of the cloud shadow seemed to affect b_{bp} , but not a_{pg} as observed in the southeastern part of Fig. 8. Further study is needed to determine b_{bp} in the absence of the influence of the cloud effects.

420 **5. CONCLUSION**

421 This study investigated the correction of atmospheric scattering and sea surface reflection 422 in the southwest region of the New Caledonia lagoon using AVNIR-2 images, which have four 423 bands from visible to NIR wavelengths with 10-m resolution (our processing was conducted 424 after averaging for 30-m (3×3) grids). We applied corrections for gas absorption, molecule 425 scattering, and $\rho_a + \rho_g$ using the iteration scheme for converging b_{bp} through IOPs from visible 426 bands. This scheme was able to correct fine structure patterns of the $\rho_a + \rho_g$ successfully. The AVNIR-2-estimated R_{rs} agreed well with the MODIS R_{rs} (root-mean square difference / 427 average of R_{rs} at 443 nm = 40%). Future projects, e.g., the Global Change Observation Mission 428 429 (GCOM), using the Second-generation Global Imager (SGLI) and the Sentinel-3 Ocean and 430 Land Colour Imager (OLCI), will have finer (250 m - 300 m) spatial resolution aiming for 431 coastal monitoring with a swath of more than 1150 km. These missions will require a correction of the surface reflection with high spatial resolution and a reduction of masked areas 432 433 in order to increase the observation frequency in the coastal areas.

With the bottom correction, the AVNIR-2-estimated IOPs agreed well with in situ IOP measurements (correlation coefficients were more than 0.9). Overcorrection appeared in the muddy bays and along the barrier reef, and it suggested that a constant bottom reflectance was not applicable in these areas.

This study showed that the AVNIR-2-estimated *Chla* from the a_{pg} regression scheme in the lagoon area does not show the overestimation observed with the blue / green R_{rs} ratio. This also confirms that the relationship between *Chla* and a_{pg} in the lagoon area is not different from the a_{pg} -*Chla* relationship of the NOMAD database as already shown in [27]. The NOMAD relationship cannot be used in bays (*e.g.*, B50), where the a_{pg} -*Chla* relationship is disturbed by absorbing mineral particles and irregular a_g due to river discharge.

444 Our atmospheric correction and IOP estimation scheme which requires only four bands in 445 the visible and NIR wavelengths can be applied to other satellite sensors, such as the MODIS 446 500-m bands, and other multi-band sensors, such as SGLI 250-m bands. The performance 447 depends on the candidate spectra of IOPs based on in situ measurements (and aerosols) in the 448 target areas. This reinforces the need to construct databases of the various spectra of IOPs and 449 aerosols in various regions through international collaboration to develop globally applicable 450 approaches. The target of this study is not to make a fixed algorithm, but demonstrate the 451 method to make local optimal estimate of the IOPs and Chla. So, the algorithm should not be 452 applied elsewhere without a similar effort *i.e.*, preparation of the candidate spectra for the 453 target areas.

454

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464

465 **APPENDIX:**

466 Calculation of TOA reflectance with gaseous absorption correction

467
$$\rho_t(b) = L_{avnir2}(b) / f_{vc}(b) \times \pi \times d^2 / F_0(b) / \cos(\theta_{sun}) / t_{oz} / t_{wv} / t_{O2}$$
(A1)

468 where
$$t_{oz} = \exp(-k_{oz}(b) \times (oz - 343.8) \times pl)$$
 (A2)

469
$$t_{wv} = \exp(-\{k_{wv}(b) \times (ptw-14.19) \times pl + k_{wv2}(b) \times ((ptw \times pl)^2 - (14.19 \times pl)^2)\})$$
(A3)

470
$$t_{O2} = \exp(-k_{O2}(b) \times (prs - 1013.25) \times 0.2095 \times pl)$$
(A4)

471
$$pl = 1 / \cos(\theta_{sun}) + 1 / \cos(\theta_{sat})$$
(A5)

 L_{avnir2} is the AVNIR-2-observed radiance [W/m²/µm/sr], b represents the AVNIR-2 spectral 472 bands, f_{vc} is the vicarious calibration factor defined as ratio of AVNIR-2 radiance to radiance 473 simulated by MODIS observation, d is the sun-earth distance [AU], F_0 is the solar irradiance at 474 1 AU [67], θ_{sun} is the solar zenith angle [rad], θ_{sat} is the satellite zenith angle [rad], oz is the 475 476 column ozone [DU], ptw is the column water vapor [mm], and prs is the sea-level pressure 477 [hPa]. The gas absorption coefficients k_{oz} , k_{wv} and k_{O2} were calculated by MODTRAN 4 [68] considering the spectral response of the AVNIR-2 bands (Table 2). We used ptw and prs from 478 479 the National Centers for Environmental Prediction (NCEP) and oz from the Ozone Monitoring 480 Instrument (OMI), which is distributed by Goddard Space Flight Center.

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707 TABLE LIST

Symbol	Description	Unit
Chla	chlorophyll-a concentration (sum of chlorophyll-a and divinyl chlorophyll-a)	mg m ⁻³
R_{rs}	remote sensing reflectance above sea surface	sr^{-1}
rs	remote sensing reflectance just bellow sea surface	sr^{-1}
O_t	top of atmosphere reflectance	-
\mathcal{O}_r	atmospheric molecule reflectance	-
\mathcal{O}_a	aerosol reflectance, including aerosol-molecule interaction	-
O_g	sunglint reflectance	-
$\hat{\mathcal{I}}_{wc}$	whitecap reflectance	-
\mathcal{D}_{w}	water-leaving reflectance	-
O_{ag}	aerosol + sea surface reflectance (= $\rho_{a} + \rho_{g} + \rho_{wc}$)	-
O_{agw}	Rayleigh-scattering subtracted reflectance	-
-ugw	atmospheric direct transmittance (sun-surface + surface-satellite)	-
Г	direct + diffuse transmittance (sun-surface + surface-satellite)	-
τ_a	aerosol optical thickness	_
M M	aerosol model number	_
λ_b	center wavelength of sensor spectral band	nm
	power function of spectral slope of ρ_{ag}	-
α	correction factor of spectral slope	-
C _{wl}	air-mass (=2 when satellite and sun are both in nadir)	-
ol T	total absorption coefficient	m^{-1}
l	absorption coefficient of water	m^{-1}
l _w ,	absorption coefficient of phytoplankton	m^{-1}
l_{ph}	absorption coefficient of detritus	m^{-1}
l _d	absorption coefficient of CDOM	m^{-1}
	absorption coefficient of particles + CDOM	m^{-1}
l_{pg} ,	model spectrum of phytoplankton absorption normalized at 442 nm	111
l_{ph}	detritus+CDOM absorption at 442 nm	- m ⁻¹
u_{dg0}	spectral slope of a_{dg} '	-
	model spectrum of detritus+CDOM absorption normalized at 442 nm	_
ι _{dg} ΄ ·	ratio of a_{ph} and a_{dg} at 442 nm	
pg	phytoplankton+detritus+CDOM absorption at 442 nm	m^{-1}
a_{pg0} a_{pg}	model spectrum of phytoplankton+detritus+CDOM absorption normalized at 442 nm	-
•рд Р _b	total backscattering coefficient	m^{-1}
, b D _w	scattering coefficient of water	m^{-1}
b_{bw}	backscattering coefficient of water	m^{-1}
bw bp	backscattering coefficient of particles	m^{-1}
р рр0	particle backscattering at 442 nm	m^{-1}
г <i>өр</i> ө 7	spectral exponent of b_{bp} '	-
bp'	model spectrum of particle backscattering normalized at 442 nm	-
ор 7 6	albedo of sea floor	-
H H	bottom depth	m
dp rs	remote-sensing reflectance for optically deep water	sr ⁻¹
rs How	subsurface solar zenith angle from nadir	radian
ю Э _w	subsurface viewing angle from nadir	radian
	above-surface viewing angle from nadir	radian
\mathcal{F}_a	attenuation coefficient	m^{-1}
r		IU
D_u^C	optical path-elongation factors for scattered photons from the water column	-
D_u^B	optical path-elongation factors for scattered photons from the bottom	-
L _{wn}	normalized water-leaving radiance	mW /µm/s

Table 1 Symbols and Definitions

Table 2 AVNIR-2 bands, cross-cal coefficients, and gas abruption coefficients					
AVNIR-2 band number (b)	1	2	3	4	
Center wavelength (λ_b) [nm]	463.0	560.0	652.1	820.6	
Solar irradiance at 1 AU (F_0) [W/m ² / μ m]	1943.3	1813.7	1562.3	1076.5	
Calibration correction coefficients (f_{vc})	0.976	1.019	1.001	0.958	
Ozone absorption coefficient (k_{oz})	1.314×10^{-5}	1.191×10 ⁻⁴		5.461×10 ⁻⁶	
Water vapor k_{wv}	0	1.763×10 ⁻⁴	2.595×10^{-4}	1.223×10^{-3}	
absorption coefficient k_{wv2}	0	0	0	-2.580×10^{-6}	
O_2 absorption coefficient (k_{O2})	0	0	0	1.352×10^{-4}	

Table 3 Spectra of a_w , b_{bw} , and a_{ph}							
	Band 1	Band 2	Band 3	Band 4	Band A	Band B	
Central wavelength (nm)	(463.0)	(560.0)	(652.1)	(820.6)	(442)	(555)	
a_w [53]	0.01085	0.07935	0.37969	3.41656	0.00684	0.05969	
<i>b_{bw}</i> [54]	0.00208	0.00091	0.00048	0.00018	0.00246	0.00093	
(i) New Caledonia a _{ph}	0.84224	0.19490	0.11668	0.0	1.0	0.19869	
(ii) Picoplankton a _{ph} [58]	0.80046	0.07025	0.11225	0.0	1.0	0.04378	
(iii) Microplankton a _{ph} [58]	0.89368	0.37280	0.37919	0.0	1.0	0.37556	

The values for bands 1-4 are weighted by the spectral response of the AVNIR-2 bands. The

Table 4 respectively. Bands A and B (at 442 nm and 555 nm, respectively) were obtained

by weighting using a rectangular response with ± 5 nm width.

a_{ph} spectra (i) is used in (A) and (D)-(F) of Table 4, (ii) and (iii) are used in (B) and (C) of

Test No.		<i>a_{ph}</i> spectrum	S	Y	AVNIR-2 a_{pg} vs. in situ			AVNIR2 vs. in situ b_{bp}		
					a_p at 442 nm×1.52			at 555 nm		
					r	bias	RMSD	r	bias	RMSD
without bottom	(A)	New Caledonia	-0.010	-1.4	0.91	0.188	0.489	0.94	0.023	0.042
	(B)	Picoplankton [58]	-0.010	-1.4	0.94	0.062	0.124	0.91	0.010	0.012
	(C)	Microplankton [58]	-0.010	-1.4	0.93	0.466	1.134+	0.91	0.056	0.119+
	(D)	New Caledonia	-0.018	-1.4	0.94	0.090	0.191 ⁻	0.93	0.012	0.015
	(E)	New Caledonia	-0.010	-0.0	0.94	0.033	0.098-	0.93	0.012	0.015
	(F)	New Caledonia	-0.010	-2.0	0.91	0.340	0.909+	0.93	0.034	0.076+
with bottom	(A)	New Caledonia	-0.010	-1.4	0.95	0.118	0.290	0.96	0.015	0.025
	(B)	Picoplankton [58]	-0.010	-1.4	0.80	-0.011	0.087^{-}	0.55	0.002	0.010-
	(C)	Microplankton [58]	-0.010	-1.4	0.93	0.458^{+}	1.132+	0.91	0.055	0.118+
	(D)	New Caledonia	-0.018	-1.4	0.91	0.016	0.059-	0.75	0.005	0.009-
	(E)	New Caledonia	-0.010	-0.0	0.72	-0.020	0.098	0.49	0.004	0.012
	(F)	New Caledonia	-0.010	-2.0	0.91	0.315	0.898+	0.93	0.031	0.074^{+}

 Table 4 Comparison between in situ and AVNIR-2 IOP estimates using different sets of IOP spectra

Sample number N=15. In situ averages of $a_p \times 1.52$ at 442 nm and b_{bp} at 555 nm were 0.099

 m^{-1} and 0.0055 m^{-1} , respectively. Superscripts $\bar{}$ and + show values that were smaller and

122 larger compared to case (A) at significance level of 95%. *S* and *Y* are defined in the text (Eqs.

723 (12) and (13)).

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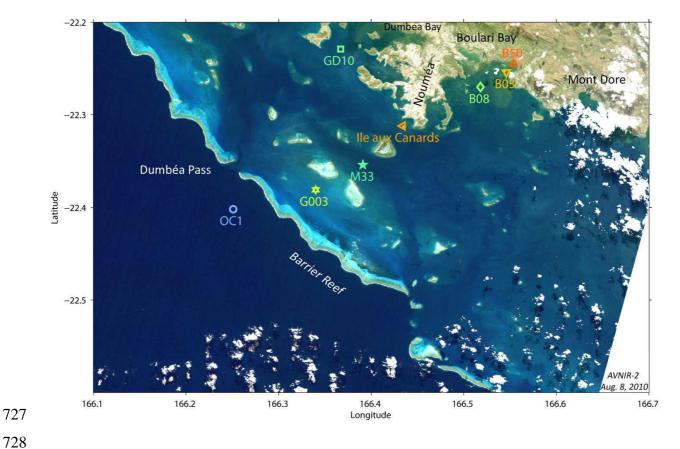
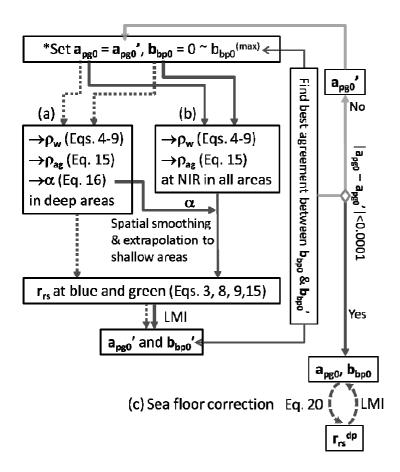




Figure 1 New Caledonia lagoon and in situ observation stations used in this study (B50, B03, B08, GD10, Ile aux Canards, M33, G003, and OC1). The background image is the RGB image of R_{rs} at 652 nm, 560 nm, and 463 nm derived from this study.



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Figure 2 Processing flow of the IOP and aerosol correction. The operation starts from *. The first flow (a) produces the α , which is used in the second flow (b). After a_{pg0} is converted $(|a_{pg0})^{\prime}$ $-a_{pg0}'| < 0.0001$), the sea-floor correction (c) is applied..

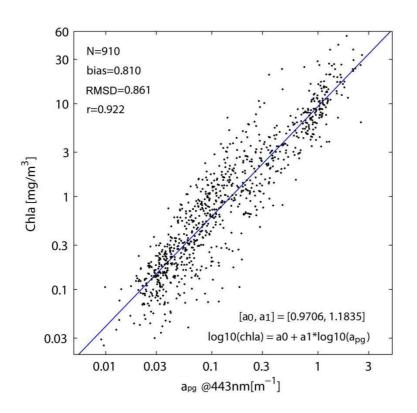




Figure 3 Relation between *Chla* and a_{pg} or blue-green R_{rs} ratio (log₁₀ base) based on NOMAD [55]. N, RMSD, and r indicate sample number, root mean square error of the regression (log₁₀ scale), and the correlation. a0 and a1 are coefficients of the linear regression, *i.e.*, log₁₀(*Chla*) = 0.9706 + 1.1835 log₁₀(a_{pg}).

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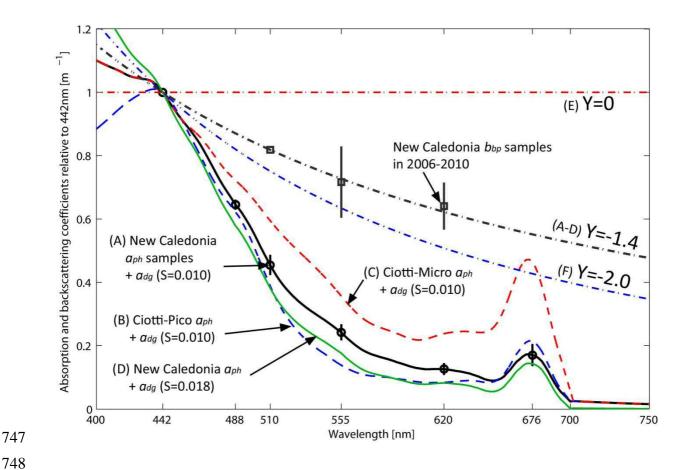




Figure 4 Model spectra of a_{pg} and b_{bp} used in this study. Models of a_{pg} (A) and b_{bp} 749 (Y=-1.4) were set from the New Caledonia measurements. S was defined as 750 $a_{dg} = \exp(S \times (\lambda - 442))$ as in Eq. (12), and Y was defined as $b_{bp} = (\lambda / 442)^{Y}$ in Eq. (13). The 751 752 spectra for picoplankton (B) and microplankton (C) from [58] were used for comparison. Curves are indicated for different Y slopes for b_{bp} (Y=0 and Y=-2, see also Table 4). Bars 753 754 show standard deviation of the in situ measurements.

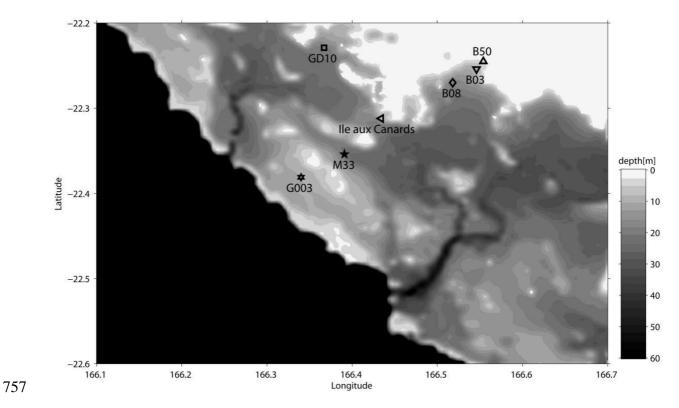
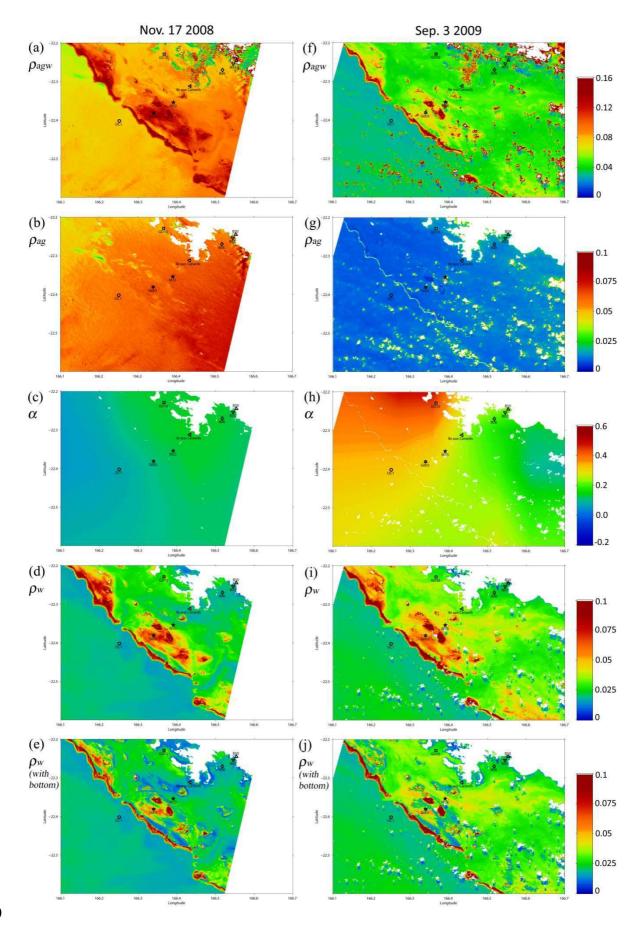


Figure 5 Bathymetry in the target area [12]. Deep areas (>60m) are filled by black.



- Figure 6 Examples of AVNIR-2-derived ρ_{agw} , ρ_{ag} , α , ρ_{w} without bottom correction, and ρ_{w} at
- 762 463 nm with bottom correction for 17 Nov 2008 (a-e) and for 3 Sep. 2009 (f-j) (using model
- 763 (A) in Table 4). The field measurement sites are shown in each panel.

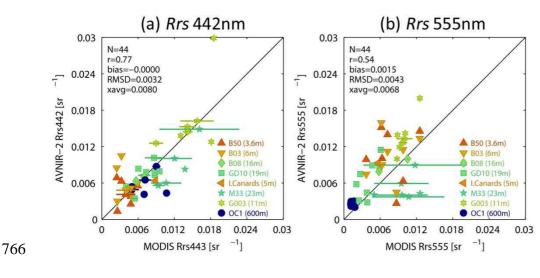


Figure 7 Comparison between AVNIR-2 *Rrs* at 442 nm and MODIS *Rrs* at 443 nm (a) and at
555 nm (b) for 44 samples. The markers distinguish between the different observation stations.
The horizontal bars show the standard deviation of the multiple MODIS scenes.



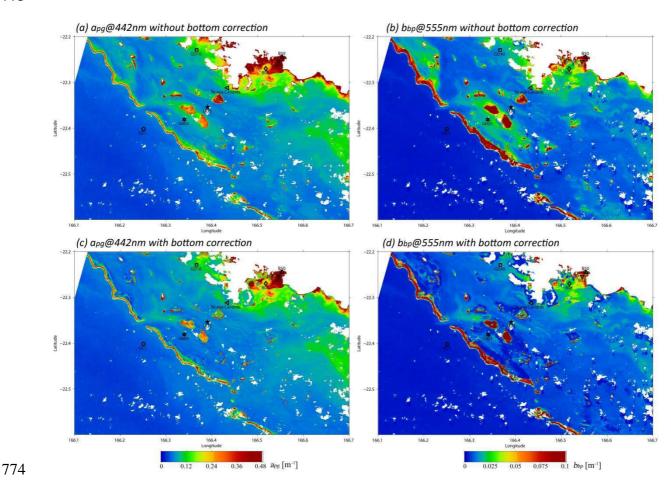


Figure 8 AVNIR-2 estimation of (a) a_{pg} at 442nm and (b) b_{bp} at 555nm on 3 Sep 2009 (using model spectra (A) in Table 4 and no correction of the bottom reflection). (c) and (d) are same as (a) and (b) except applying the correction of the bottom reflection. Markers show in situ observation stations.

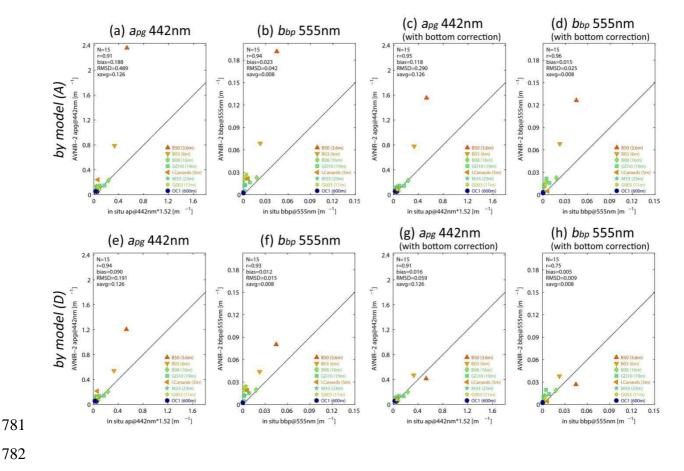


Figure 9 Scatter diagrams of (a) AVNIR-2 a_{pg} and in situ a_p (×1.52) at 442 nm, (b) b_{bp} at 555 nm from model (A) in Table 4. (c) and (d) are same as (a) and (b) except applying the correction of the bottom reflection. N, r, bias, and RMSD, indicate sample number, correlation coefficient, bias of AVNIR-2 from in situ, and root mean square difference. xavg indicates the average of in situ data (in m⁻¹). (e)-(h) are same as (a)-(d) except they are derived from model (D).

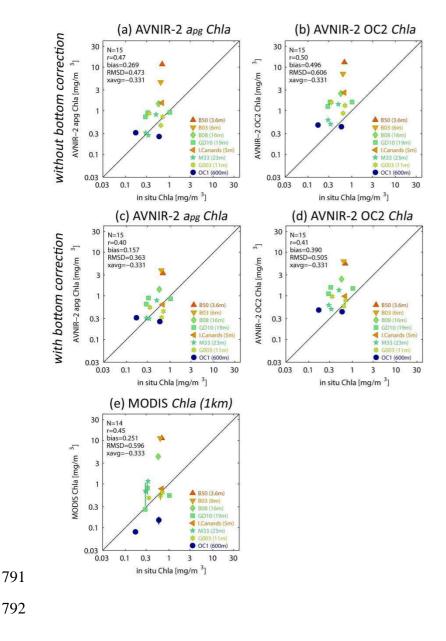


Figure 10 Scatter diagrams of in situ *Chla* and (a) *Chla* from AVNIR-2 a_{pg} , (b) *Chla* from AVNIR-2 OC2M-HI, (c) and (d) are same as (a) and (b) except applying the bottom correction, (e) *Chla* from the MODIS standard OC3M (1 km), and (f) the scatter plot between AVNIR-2 a_{pg} *Chla* and the MODIS OC3M *Chla*. Bars show the standard deviation of the multiple MODIS scenes around the AVNIR-2 observation dates or the standard deviation of 3×3 pixels of AVNIR-2 data. N, r, bias, RMSD, and xvag show sample number, correlation coefficient, bias, root mean square difference, and the average of x-axis variables in log_{10} scale.

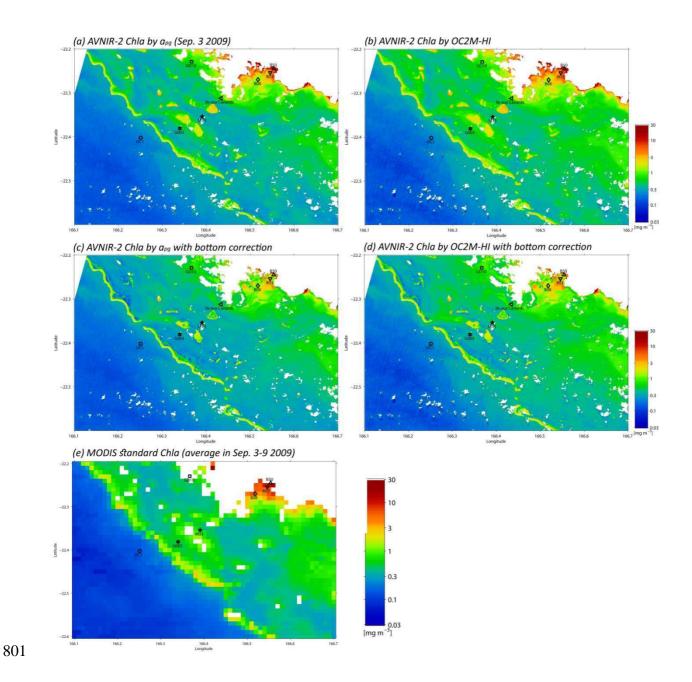


Figure 11 (a), (b), and (e) are *Chla* from a_{pg} , *Chla* from OC2M-HI (Sep. 3 2009) and the MODIS standard *Chla* (average from Sep. 3 to Sep. 9 in 2009). (c) and (d) are the same as (a) and (b) except applying the bottom correction. Markers show the in situ observation stations on Sep 9 2009.